



32Mb Async. FAST SRAM B-die

Asynchronous FAST SRAM

1.65V ~ 3.6V

- **S6R3216W1B 48TSOP1**

Datasheet

Features

- Fast Access Time : 10ns, 12ns
- Wide range of Power Supply
- 1.65V ~ 3.6V
- TTL Compatible Inputs and Outputs
- Three State Outputs
- Data Byte Control(x16 Mode)
 \overline{LB} : I/O7~ I/O0, \overline{UB} : I/O15~ I/O8
- Standard 48TSOP1 Package
- ROHS compliant
- Operating in Industrial Temperature range

Performance

| Operation | Symbol | Typical Value | | | Unit |
|---------------------|-----------|---------------|----------|----------|------|
| | | 3.3V | 2.5V | 1.8V | |
| Read Cycle Time | t_{RC} | 10(min.) | 12(min.) | 15(min.) | ns |
| Address Access Time | t_{AA} | 10(min.) | 12(min.) | 15(min.) | ns |
| Write Cycle Time | t_{WC} | 10(min.) | 12(min.) | 15(min.) | ns |
| Standby Current | I_{SB1} | 10.0 | 10.0 | 10.0 | mA |
| Operating Current | I_{CC} | 45 | 43 | 40 | mA |

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General Description

The S6R3216W1B is a 33,578,432-bit high-speed Static Random Access Memory organized as 2M words by 16 bits. The S6R3216W1B uses 16 common input and output lines and have an output enable pin which operates faster than address access time at read cycle.

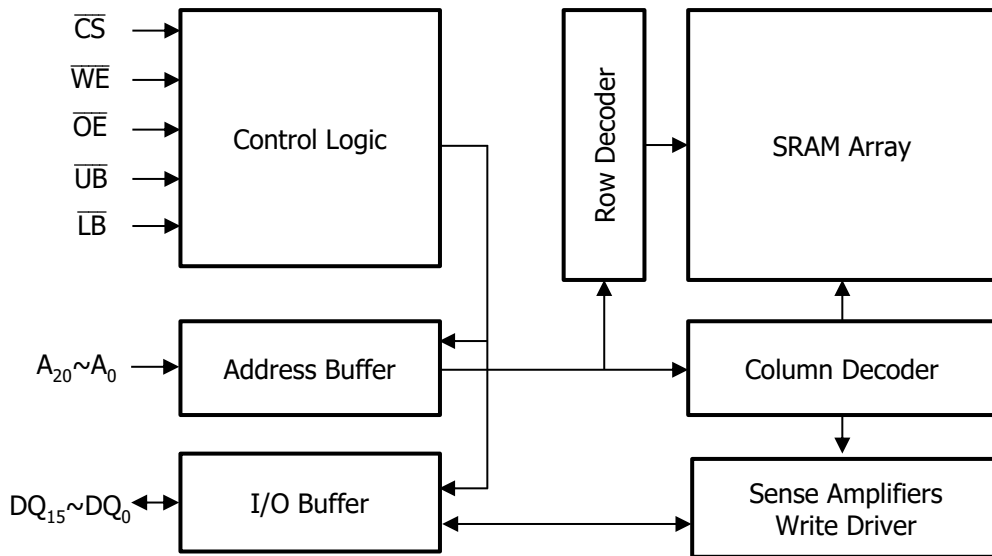
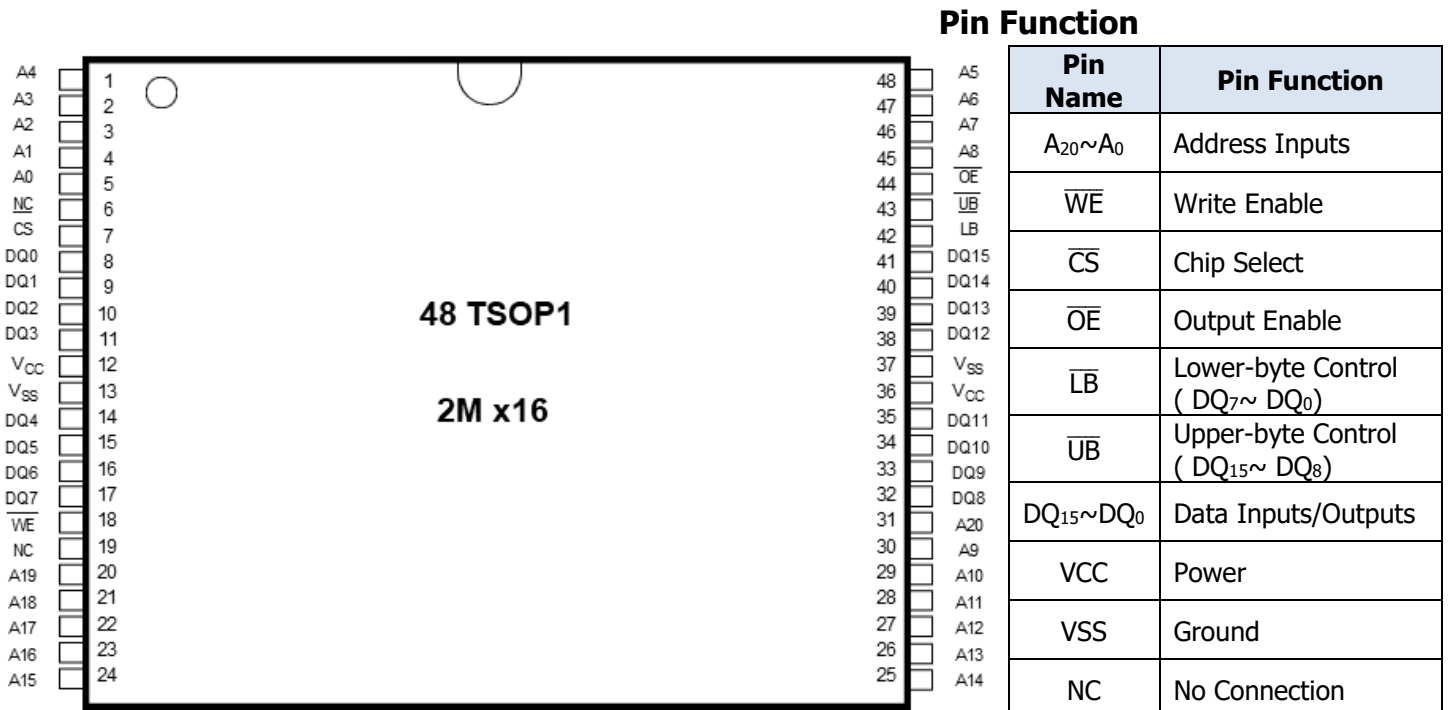
And S6R3216W1B allows that lower and upper byte access by data byte control(\overline{LB} , \overline{UB}). The device is fabricated using advanced CMOS process, 6-TR based cell technology and designed for high-speed circuit technology.

It is particularly well suited for use in high-reliable and high-speed system applications.

The S6R3216W1B is packaged in 48TSOP1.

Asynchronous FAST SRAM Ordering Information

| Density | Org. | Part Number | Vcc(V) | Speed (ns) | | Package | Temperature |
|---------|--------|-----------------|--------|------------|-----|---------|------------------------|
| | | | | tAA | tOE | | |
| 32Mb | 2M x16 | S6R3216W1B-YI10 | 3.3 | 10 | 5 | 48TSOP1 | Industrial Temperature |
| | | | 2.5 | 12 | 6 | | |
| | | | 1.8 | 15 | 7 | | |

Logic Block Diagram – S6R3216W1B (2M x16)

48TSOP1 Package Pin Configuration (Top View) – S6R3216W1B (2M x16)


Absolute Maximum Ratings

| Parameter | Symbol | Rating | Units |
|---------------------------------------|------------------|------------------|-------|
| Voltage on Vcc Supply Relative to VSS | Vin, Vout | -0.5 to Vcc+0.5V | V |
| Voltage on Any Pin Relative to VSS | Vin, Vout | -0.5 to 4.0 | V |
| Power Dissipation | P _D | 1.0 | W |
| Storage Temperature | P _{STG} | -65 to 150 | °C |
| Operating Ambient Temperature | T _A | -40 to 85 | °C |

* Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operating sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

Recommended DC Operating Conditions

| Parameter | Operating Vcc(V) | Symbol | Min. | Typ. | Max. | Units |
|--------------------|------------------|-----------------|------|---------|---------|-------|
| Vcc Supply Voltage | 2.3 ~ 3.6 | Vcc | 2.3 | 2.5/3.3 | 3.6 | V |
| | 1.65 ~ 2.2 | Vcc | 1.65 | 1.8 | 2.2 | V |
| Ground | | Vss | 0 | 0 | 0 | V |
| Input High Voltage | 2.3 ~ 3.6 | V _{IH} | 2.0 | - | Vcc+0.3 | V |
| | 1.65 ~ 2.2 | V _{IH} | 1.4 | - | Vcc+0.2 | V |
| Input Low Voltage | 2.3 ~ 3.6 | V _{IL} | -0.3 | - | 0.7 | V |
| | 1.65 ~ 2.2 | V _{IL} | -0.2 | - | 0.4 | V |

DC and Operating Characteristics

| Parameters | Symbol | Test Conditions | Min | Typ | Max | Unit | |
|------------------------|-----------|---|------|-----|-----|------|----|
| Input Leakage Current | I_{LI} | $V_{IN} = V_{SS} \text{ to } V_{CC}$ | -2 | - | +2 | uA | |
| Output Leakage Current | I_{LO} | $\overline{CS}=V_{IH}$ or $\overline{OE}=V_{IH}$ or $\overline{WE}=V_{IL}$ $V_{OUT} = V_{SS} \text{ to } V_{CC}$ | -2 | - | +2 | uA | |
| Operating Current | I_{CC} | $V_{CC}(\text{max}), f=f_{\text{max}}, I_{OUT}=0\text{mA}$ $V_{IN} \geq V_{CC}-0.2\text{V}$ or $V_{IN} \leq 0.2\text{V}$ | 10ns | - | 45 | 80 | mA |
| | | | 12ns | - | 43 | 76 | |
| | | | 15ns | - | 40 | 72 | |
| Standby Current | I_{SB} | $V_{CC}(\text{max}), f=f_{\text{max}}, \overline{CS} \geq V_{IH}$ | - | - | 60 | mA | |
| | I_{SB1} | $V_{CC}(\text{max}), f=0, \overline{CS} \geq V_{CC}-0.2\text{V}$ $V_{IN} \geq V_{CC}-0.2\text{V}$ or $V_{IN} \leq 0.2\text{V}$ | - | 10 | 36 | | |
| Output Low Voltage | V_{OL} | $V_{CC}=3.0\text{V}, I_{OL}=8\text{mA}$ | - | - | 0.4 | V | |
| | | $V_{CC}=2.4\text{V}, I_{OL}=1\text{mA}$ | - | - | 0.4 | | |
| | | $V_{CC}=1.65\text{V}, I_{OL}=0.1\text{mA}$ | - | - | 0.2 | | |
| Output High Voltage | V_{OH} | $V_{CC}=3.0\text{V}, I_{OH}=-4\text{mA}$ | 2.4 | - | - | V | |
| | | $V_{CC}=2.4\text{V}, I_{OH}=-1\text{mA}$ | 1.8 | - | - | | |
| | | $V_{CC}=1.65\text{V}, I_{OH}=-0.1\text{mA}$ | 1.4 | - | - | | |

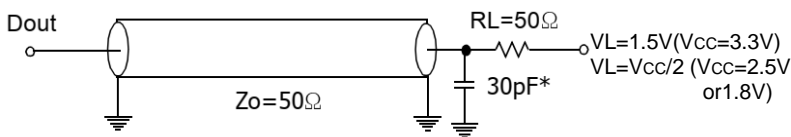
Pin Capacitance

| Item | Symbol | Test Conditions | Typ | Max | Unit |
|--------------------------|-----------|---------------------|-----|-----|------|
| Input/Output Capacitance | $C_{I/O}$ | $V_{I/O}=0\text{V}$ | - | 10 | pF |
| Input Capacitance | C_{IN} | $V_{IN}=0\text{V}$ | - | 16 | pF |

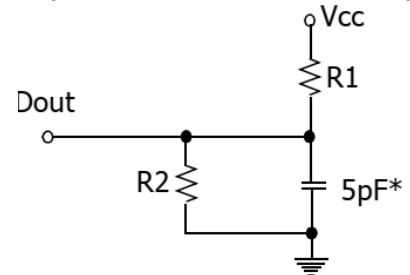
* $T_A=25^\circ\text{C}$, $f=1.0\text{MHz}$, Capacitance is sampled and not 100% tested.

Test Conditions

| Parameter | Value |
|--|--|
| Input Pulse Level | 0 to 3.0V (V _{CC} =3.3V) |
| | 0 to 2.5V (V _{CC} =2.5V) |
| | 0 to 1.8V (V _{CC} =1.8V) |
| Input Rise and Fall Time | 1V/1ns |
| Input and Output Timing Reference Levels | 1.5V (V _{CC} =3.3V) |
| | 1/2V _{CC} (V _{CC} =2.5V or 1.8V) |
| Output Load | See Fig. 1 |

Output Load (A)

Output Load(B)

(for tHZ, tLZ, tWHZ, tOLZ & tOHZ)



| | | | |
|-----------------------|------|-------|--------|
| V_{CC} | 3.3V | 2.5V | 1.8V |
| R1 | 319Ω | 1909Ω | 13500Ω |
| R2 | 353Ω | 1105Ω | 10800Ω |

* Including Scope and Jig Capacitance

Functional Description (x16 Mode)

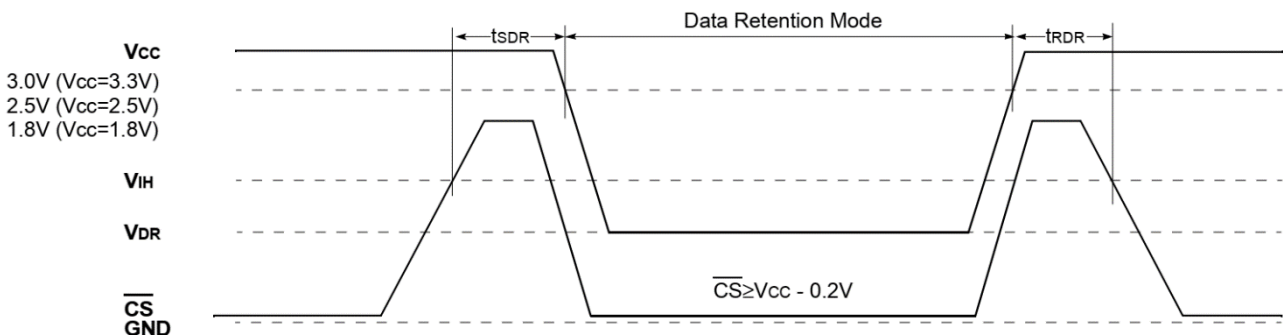
| $\overline{\text{CS}}$ | WE | $\overline{\text{OE}}$ | LB | UB | Modes | DQ Pins | | Supply Current |
|------------------------|----|------------------------|----|----|----------------|----------------------------------|-----------------------------------|---------------------------------|
| | | | | | | DQ ₇ ~DQ ₀ | DQ ₁₅ ~DQ ₈ | |
| H | X | X* | X | X | Not Selected | High-Z | High-Z | $I_{\text{SB}}, I_{\text{SB1}}$ |
| L | H | H | X | X | Output Disable | High-Z | High-Z | I_{CC} |
| L | X | X | H | H | | | | |
| L | H | L | L | H | Read | Dout | High-Z | I_{CC} |
| | | | H | L | | High-Z | Dout | |
| | | | L | L | | Dout | Dout | |
| L | L | X | L | H | Write | Din | High-Z | I_{CC} |
| | | | H | L | | High-Z | Din | |
| | | | L | L | | Din | Din | |

* X means Don't Care.

Data Retention Characteristics

| Parameter | Operating Vcc(V) | Symbol | Test Condition | Min. | Typ. | Max. | Unit |
|----------------------------|------------------|--------|---|---|------|------|------|
| Vcc for Data Retention | 2.5/3.3 | VDR | $\overline{\text{CS}} \geq V_{\text{CC}} - 0.2\text{V}$ | 2.0 | - | - | V |
| | 1.8 | | | 1.5 | - | - | |
| Data Retention Current | 2.5/3.3 | IDR | Vcc=2.0V $\overline{\text{CS}} \geq V_{\text{CC}} - 0.2\text{V}$ $V_{\text{IN}} \geq V_{\text{CC}} - 0.2\text{V}$ or $V_{\text{IN}} \leq 0.2\text{V}$ | - | 10 | 36 | mA |
| | 1.8 | | | Vcc=1.5V $\overline{\text{CS}} \geq V_{\text{CC}} - 0.2\text{V}$ $V_{\text{IN}} \geq V_{\text{CC}} - 0.2\text{V}$ or $V_{\text{IN}} \leq 0.2\text{V}$ | - | 10 | |
| Data Retention Set-Up Time | | tSDR | See Data Retention Wave form(below) | 0 | - | - | ns |
| Recovery Time | | tRDR | | 1 | - | - | ms |

Data Retention Wave Form ($\overline{\text{CS}}$ Controlled)



AC Timing Parameters

Read Cycle

| Parameter | Symbol | 10ns | | 12ns | | 15ns | | Units |
|--|-----------|------|------|------|------|------|------|-------|
| | | Min. | Max. | Min. | Max. | Min. | Max. | |
| Read Cycle Time | t_{RC} | 10 | - | 12 | - | 15 | - | ns |
| Address Access Time | t_{AA} | - | 10 | - | 12 | - | 15 | ns |
| Chip Enable to Output | t_{CO} | - | 10 | - | 12 | - | 15 | ns |
| Output Enable to Valid Output | t_{OE} | - | 5 | - | 6 | - | 7 | ns |
| \overline{UB} , \overline{LB} Access Time ¹⁾ | t_{BA} | - | 5 | - | 6 | - | 7 | ns |
| Chip Enable to Low-Z Output | t_{LZ} | 3 | - | 3 | - | 3 | - | ns |
| Output Enable to Low-Z Output | t_{OLZ} | 0 | - | 0 | - | 0 | - | ns |
| \overline{UB} , \overline{LB} Enable to Low-Z Output ¹⁾ | t_{BLZ} | 0 | - | 0 | - | 0 | - | ns |
| Chip Disable to High-Z Output | t_{HZ} | 0 | 5 | 0 | 6 | 0 | 7 | ns |
| Output Disable to High-Z Output | t_{OHZ} | 0 | 5 | 0 | 6 | 0 | 7 | ns |
| \overline{UB} , \overline{LB} Disable to High-Z Output ¹⁾ | t_{BHZ} | 0 | 5 | 0 | 6 | 0 | 7 | ns |
| Output Hold from Address Change | t_{OH} | 3 | - | 3 | - | 3 | - | ns |
| Chip Selection to Power Up Time | t_{PU} | 0 | - | 0 | - | 0 | - | ns |
| Chip Selection to Power Down Time | t_{PD} | - | 10 | - | 12 | - | 15 | ns |

Notes:

1. Those parameters are applied for x16 mode only.

Write Cycle

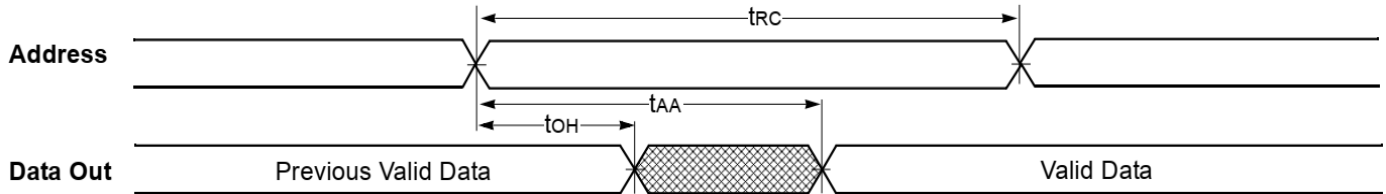
| Parameter | Symbol | 10ns | | 12ns | | 15ns | | Units |
|---|-----------|------|------|------|------|------|------|-------|
| | | Min. | Max. | Max. | Max. | Max. | Max. | |
| Write Cycle Time | t_{WC} | 10 | - | 12 | - | 15 | - | ns |
| Chip Enable to End of Write | t_{CW} | 7 | - | 9 | - | 12 | - | ns |
| Address Set-up Time | t_{AS} | 1 | - | 1 | - | 1 | - | ns |
| Address Valid to End of Write | t_{AW} | 7 | - | 9 | - | 12 | - | ns |
| Write Pulse Width (\overline{OE} High) | t_{WP} | 7 | - | 9 | - | 12 | - | ns |
| Write Pulse Width (\overline{OE} Low) | t_{WP1} | 10 | - | 12 | - | 15 | - | ns |
| \overline{UB} , \overline{LB} Valid to End of Write ¹⁾ | t_{BW} | 7 | - | 9 | - | 12 | - | ns |
| Write Recovery Time | t_{WR} | 1 | - | 1 | - | 1 | - | ns |
| Write to Output High-Z | t_{WHZ} | 0 | 5 | 0 | 6 | 0 | 7 | ns |
| Data to Write Time Overlap | t_{DW} | 5 | - | 7 | - | 8 | - | ns |
| Data Hold from Write Time | t_{DH} | 0 | - | 0 | - | 0 | - | ns |
| End of Write to Output Low-Z | t_{OW} | 3 | - | 3 | - | 3 | - | ns |

Notes:

1. Those parameters are applied for x16 mode only.

Timing Diagrams

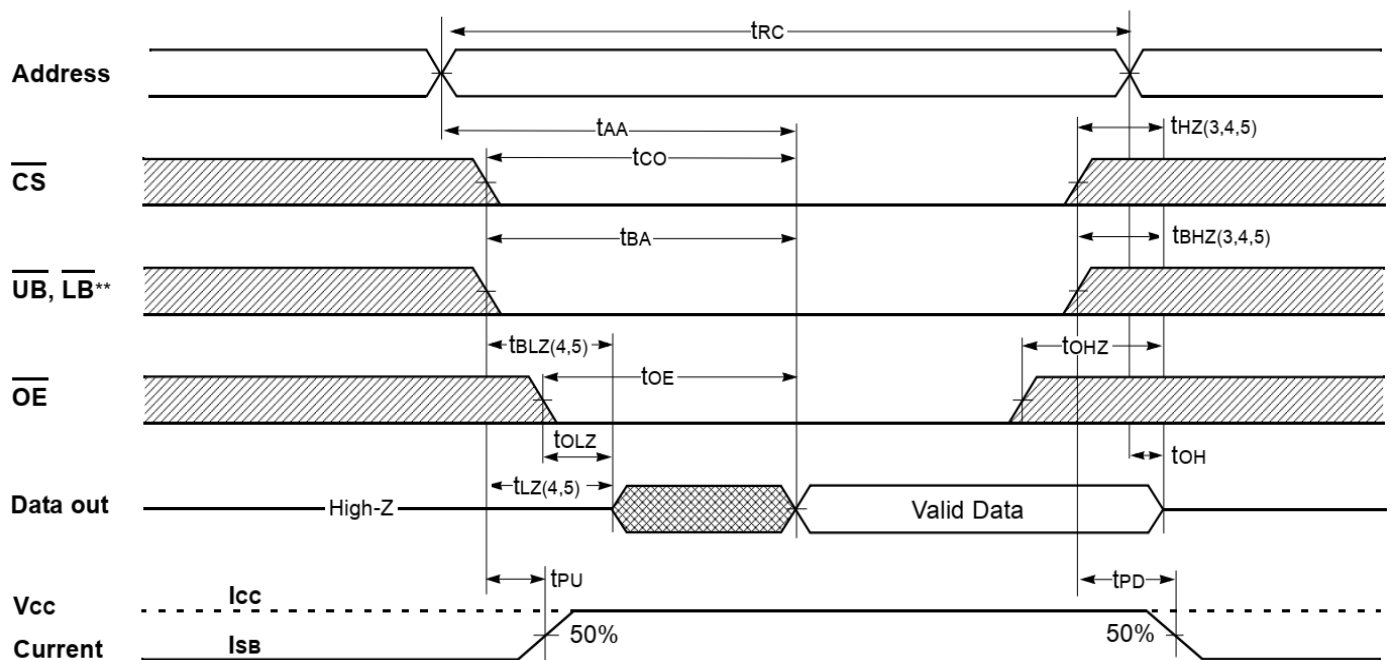
Timing Waveform of Read Cycle(1) (Address Controlled, $\overline{CS} = \overline{OE} = VIL$, $\overline{WE} = VIH$, \overline{UB} , $\overline{LB} = VIL$ ¹)



Notes:

1. Those parameters are applied for x16 mode only.

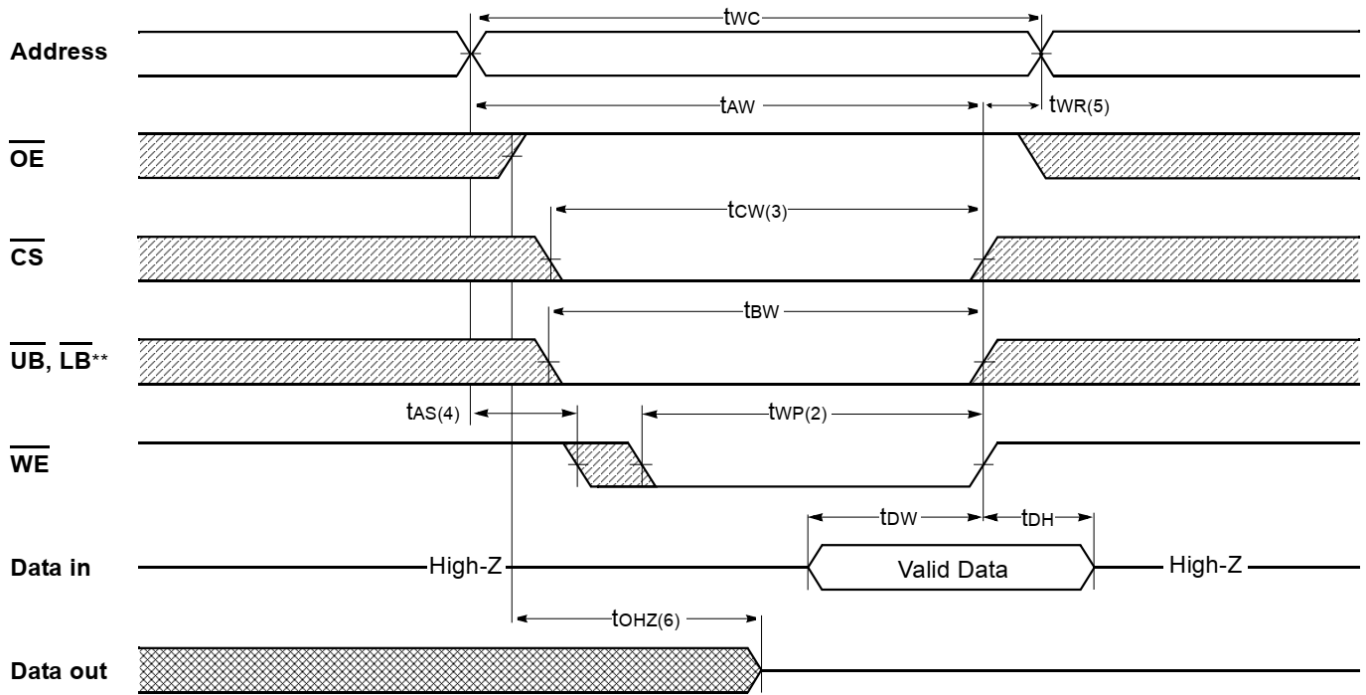
Timing Waveform of Read Cycle(2) ($\overline{WE} = VIH$)



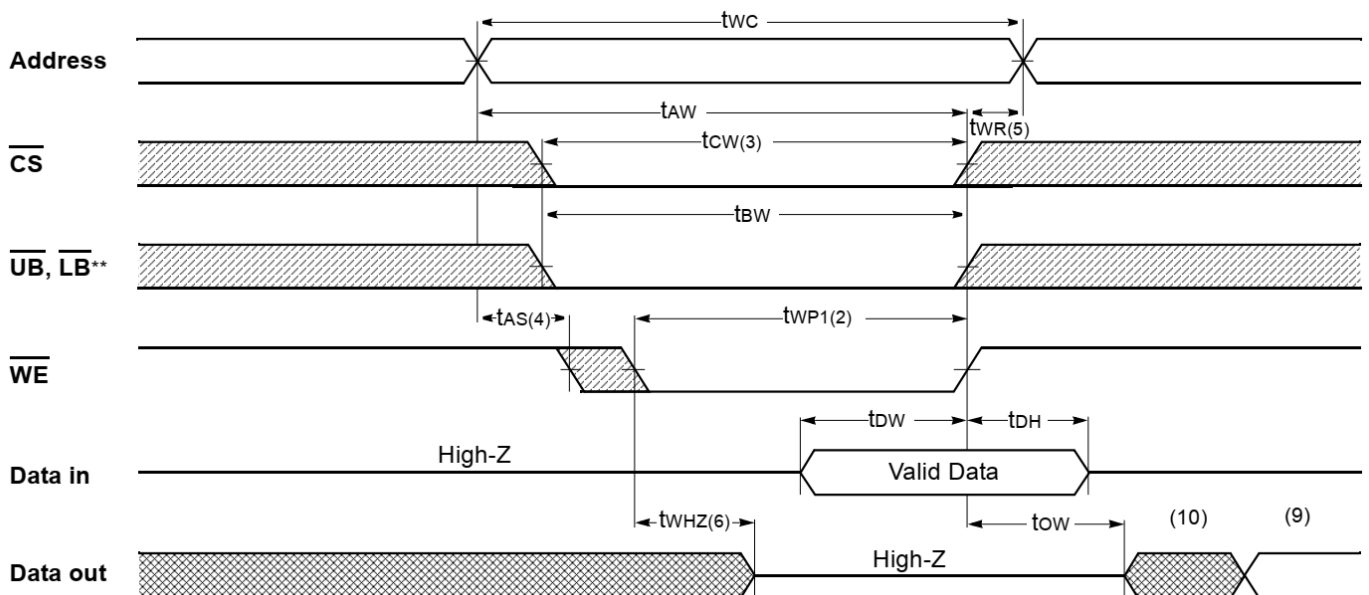
Notes (Read Cycle)

1. \overline{WE} is high for read cycle.
2. All read cycle timing is referenced from the last valid address to the first transition address.
3. tHZ and tOHZ are defined as the time at which the outputs achieve the open circuit condition and are not referenced to VOH or VOL levels.
4. At any given temperature and voltage condition, tHZ(Max.) is less than tLZ(Min.) both for a given device and from device to device.
5. Transition is measured $\pm 200mV$ from steady state voltage with Load(B). This parameter is sampled and not 100% tested.
6. Device is continuously selected with $\overline{CS} = VIL$.
7. Address valid prior to coincident with \overline{CS} transition low.
8. For common DQ applications, minimization or elimination of bus contention conditions is necessary during read and write cycle.

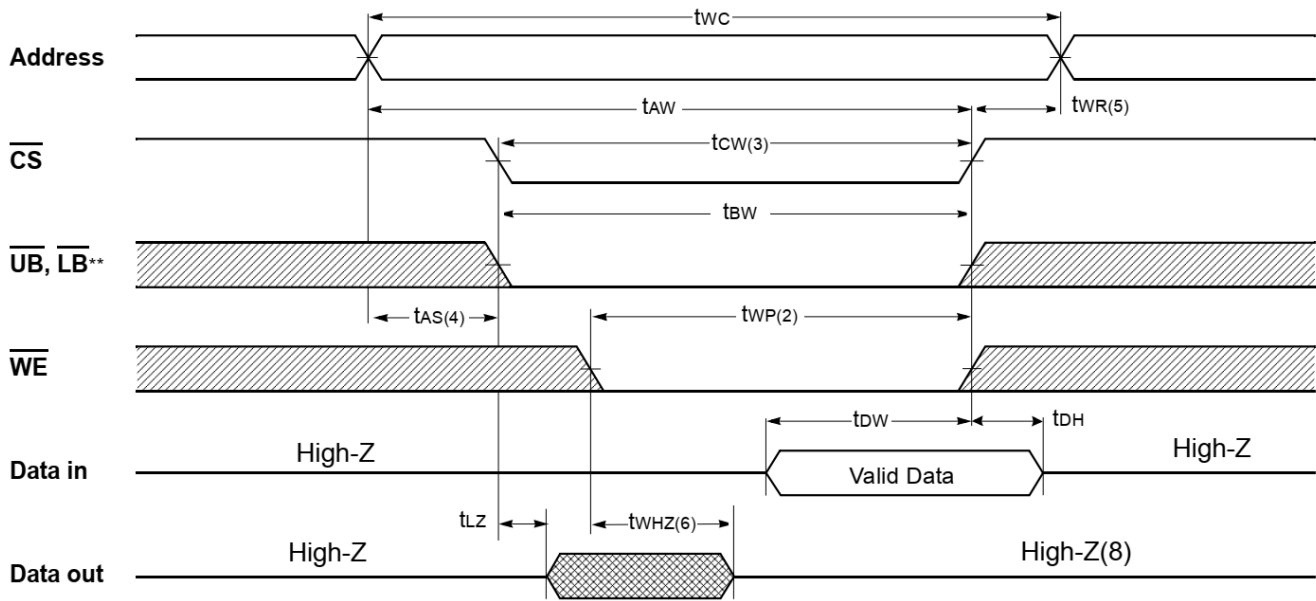
** Those parameters are applied for x16 mode only.

Timing Waveform of Write Cycle(1) (\overline{OE} Clock)


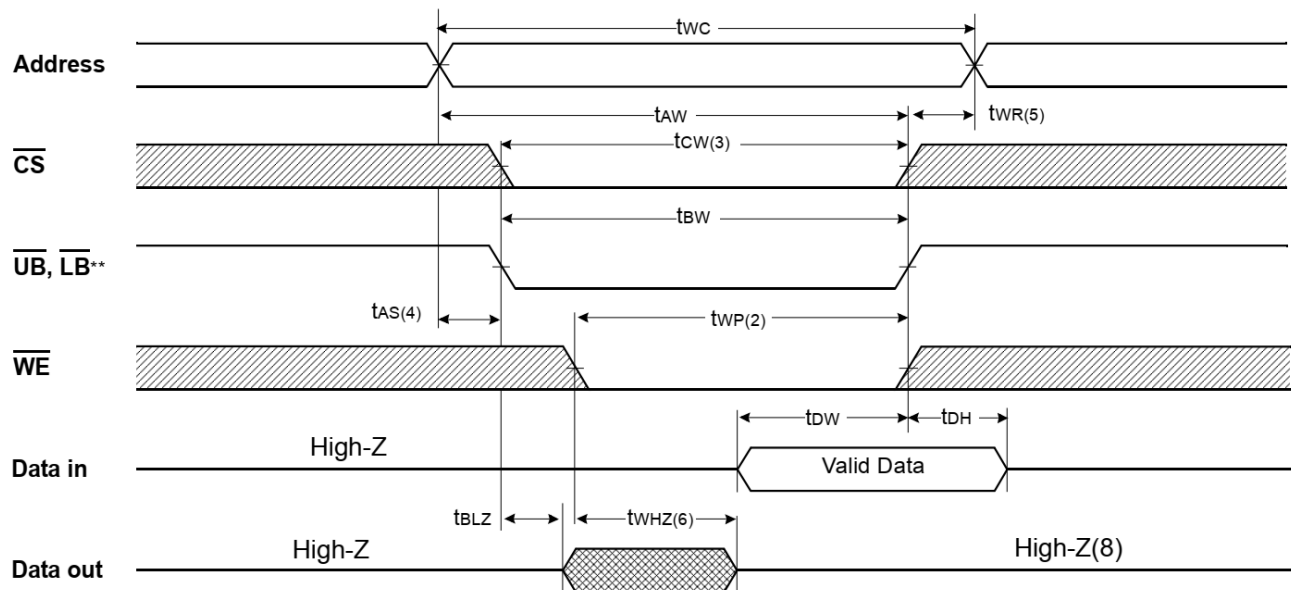
** Those parameters are applied for x16 mode only.

Timing Waveform of Write Cycle(2) (\overline{OE} = Low Fix)


** Those parameters are applied for x16 mode only.

Timing Waveform of Write Cycle(3) (\overline{CS} Controlled)


** Those parameters are applied for x16 mode only.

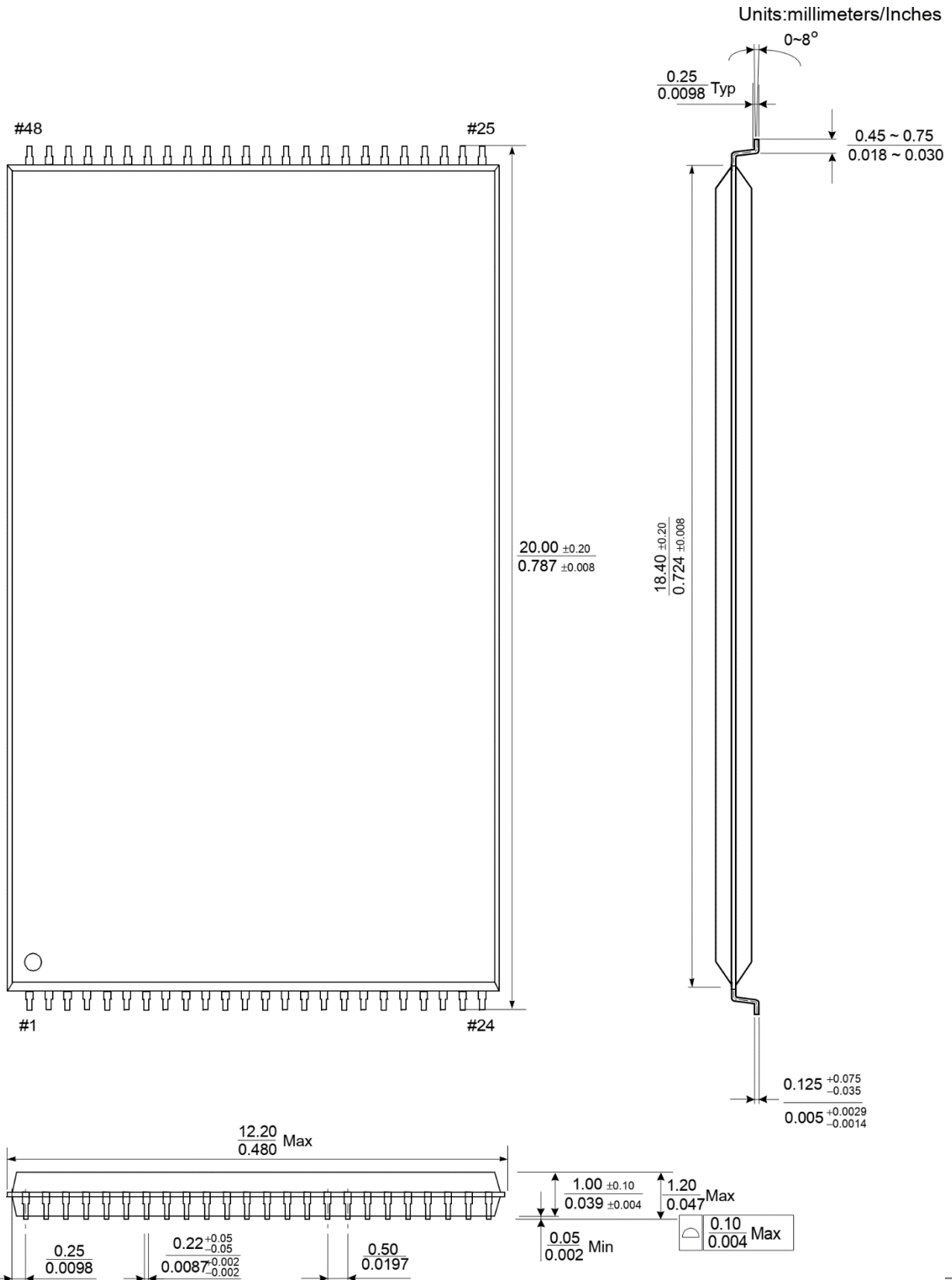
Timing Waveform of Write Cycle(4) (\overline{UB} , \overline{LB} Controlled)

Notes (Write Cycle)

1. All write cycle timing is referenced from the last valid address to the first transition address.
2. A write occurs during the overlap of a low \overline{CS} , \overline{WE} , \overline{LB} and \overline{UB} . A write begins at the latest transition \overline{CS} going low and \overline{WE} going low ; A write ends at the earliest transition \overline{CS} going high or \overline{WE} going high. tWP is measured from the beginning of write to the end of write.
3. tCW is measured from the later of \overline{CS} going low to end of write.
4. tAS is measured from the address valid to the beginning of write.
5. tWR is measured from the end of write to the address change. tWR applied in case a write ends as \overline{CS} or \overline{WE} going high.
6. If \overline{OE} , \overline{CS} and \overline{WE} are in the Read Mode during this period, the I/O pins are in the output low-Z state. Inputs of opposite phase of the output must not be applied because bus contention can occur.
7. For common I/O applications, minimization or elimination of bus contention conditions is necessary during read and write cycle.
8. If \overline{CS} goes low simultaneously with \overline{WE} going or after \overline{WE} going low, the outputs remain high impedance state.
9. $Dout$ is the read data of the new address.
10. When \overline{CS} is low : I/O pins are in the output state. The input signals in the opposite phase leading to the output should not be applied.

** Those parameters are applied for x16 mode only.

Package Dimensions

48-TSOP1



Revision History

| Revision | Date | Description |
|-----------------|-------------|--|
| 0.0 | Aug. 2023 | Initial Release, Preliminary |
| 1.0 | Jun. 2024 | 1. Remove Preliminary status 2. Update DC Characteristics |
| 1.1 | Sep. 2024 | Add 48TSOP1 package |
| 1.2 | Feb. 2025 | 1. The data sheet separates the 48FBGA package and the 48TSOP1 package. 2. Update Write Cycle in 48TSOP1 package. (tAS, tWR) 3. 48TSOP1 PKG supports 1.8V Vcc change from 12ns to 15ns and 2.5V Vcc change from 10ns to 12ns. 4. Update Pin Capacitance |

* Products and specifications discussed herein are subject to change by Netsol without notice.